

EMBC Tutorial on Interpretable and Transparent Deep Learning



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13:30 - 14:00	Introduction KRM
14:00 - 15:00	Techniques for Interpretability GM
15:00 - 15:30	Coffee Break ALL
15:30 - 16:15	Evaluating Interpretability & Applications WS
16:15 - 17:15	Applications in BME & the Sciences and Wrap-Up KRM



Why interpretability?

Why interpretability?

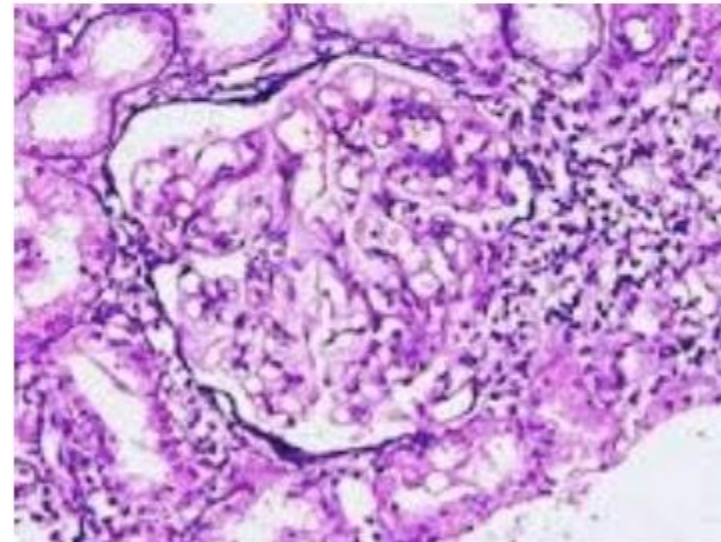
1) Verify that classifier works as expected

Wrong decisions can be costly and dangerous

“Autonomous car crashes, because it wrongly recognizes ...”

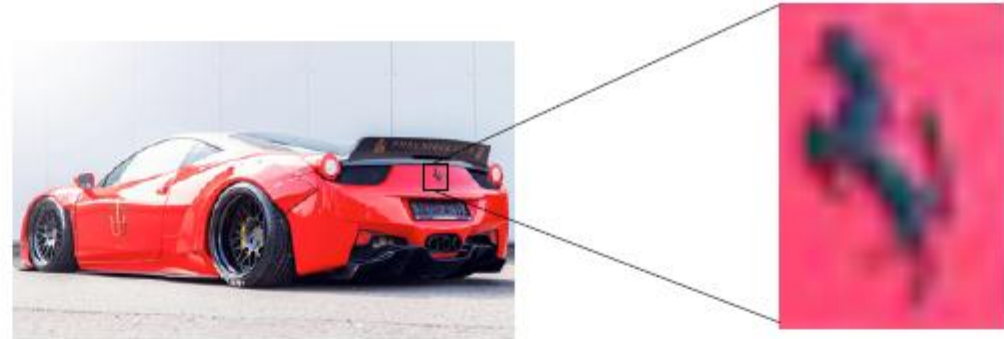


“AI medical diagnosis system misclassifies patient’s disease ...”

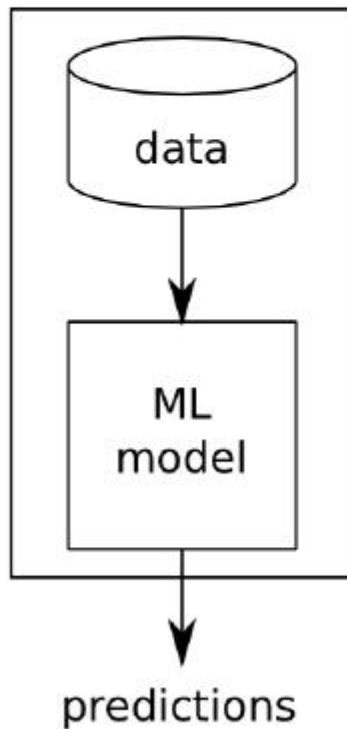


Why interpretability?

2) Improve classifier

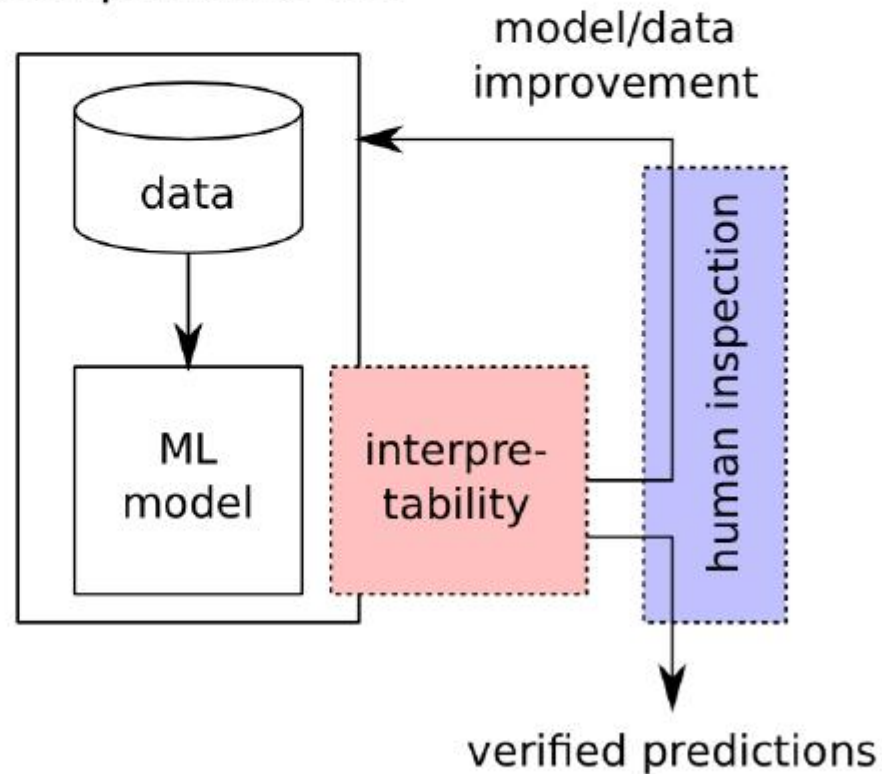


Standard ML



Generalization error

Interpretable ML



Generalization error + human experience

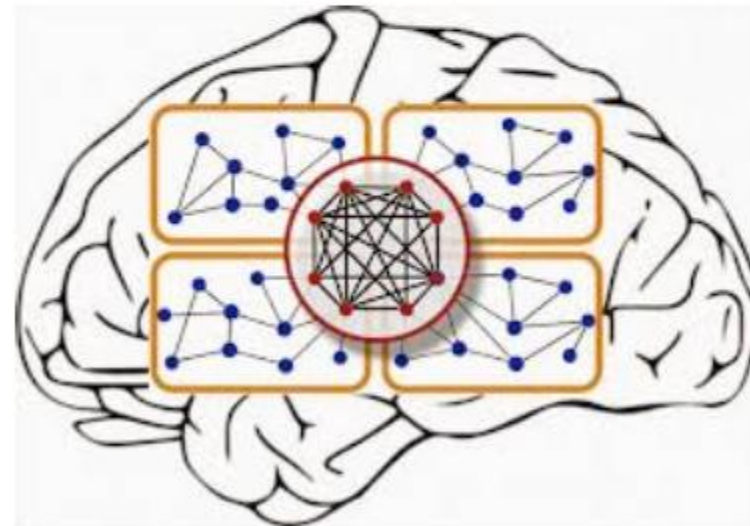
Why interpretability?

3) Learn from the learning machine

"It's not a human move. I've never seen a human play this move." (Fan Hui)



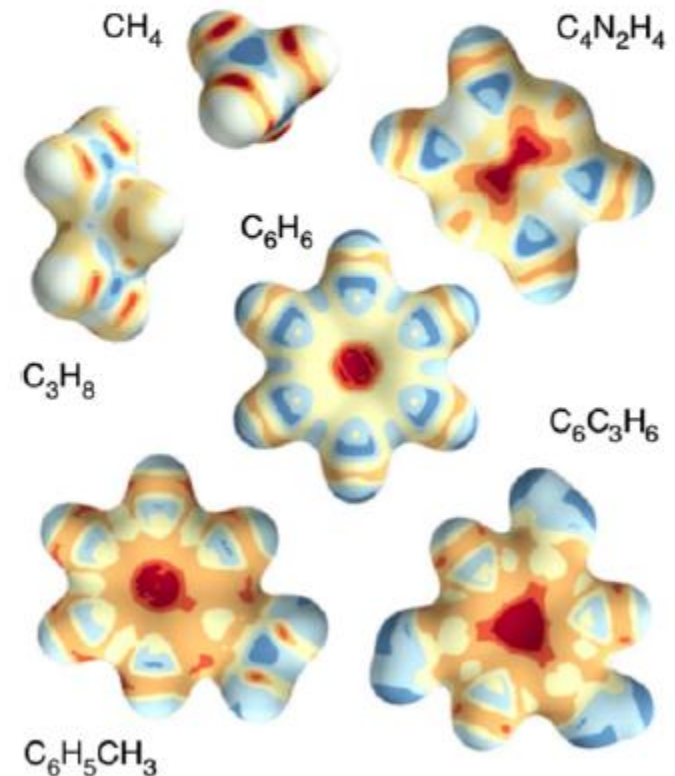
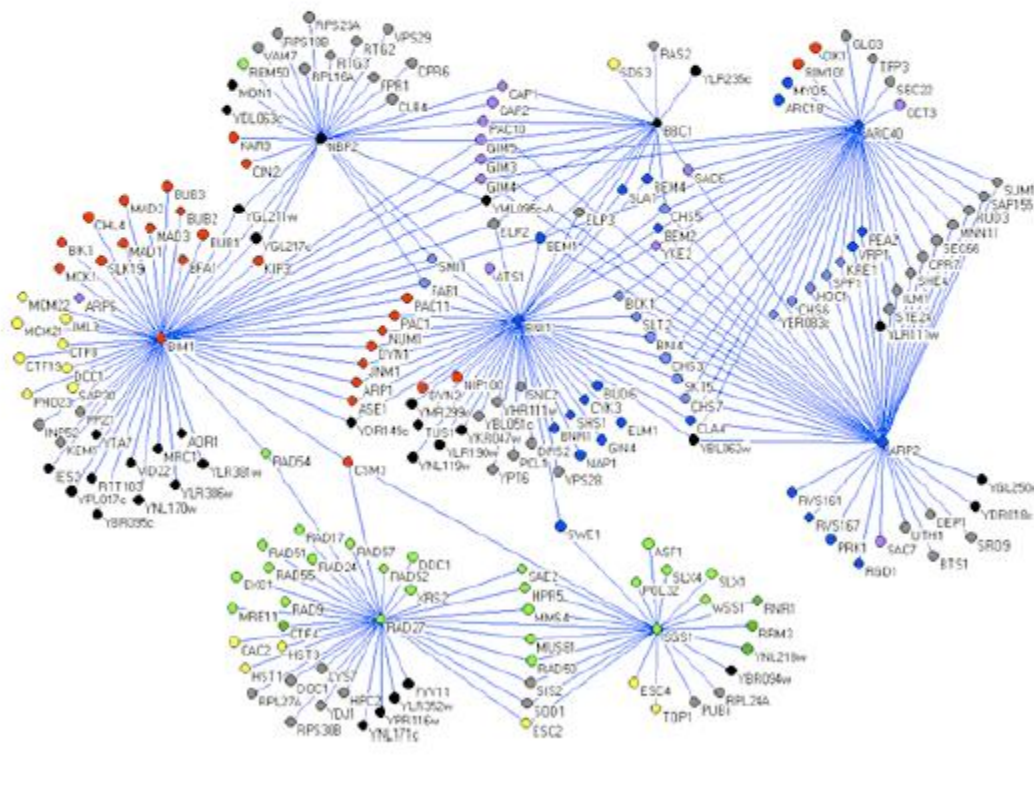
Old promise:
"Learn about the human brain."



Why interpretability? Insights!

4) Interpretability in the sciences

Learn about the physical / biological / chemical mechanisms.
(e.g. find genes linked to cancer, identify binding sites ...)



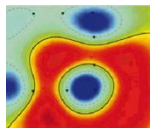
Why interpretability?

5) Compliance to legislation

European Union's new General Data Protection Regulation → “right to explanation”

Retain human decision in order to assign responsibility.

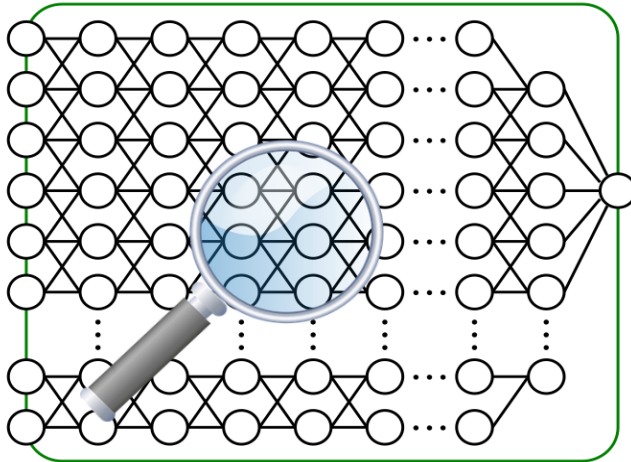
“With interpretability we can ensure that ML models work in compliance to proposed legislation.”



Overview and Intuition for different
Techniques: sensitivity, deconvolution,
LRP and friends.

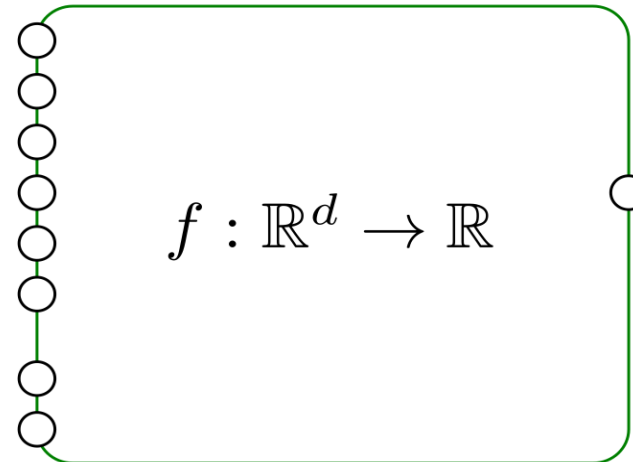
Understanding Deep Nets: Two Views

mechanistic
understanding



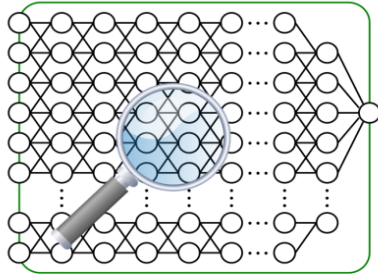
Understanding what mechanism the network uses to solve a problem or implement a function.

functional
understanding

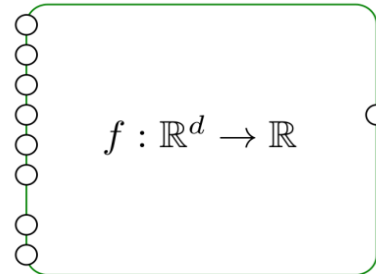


Understanding how the network relates the input to the output variables.

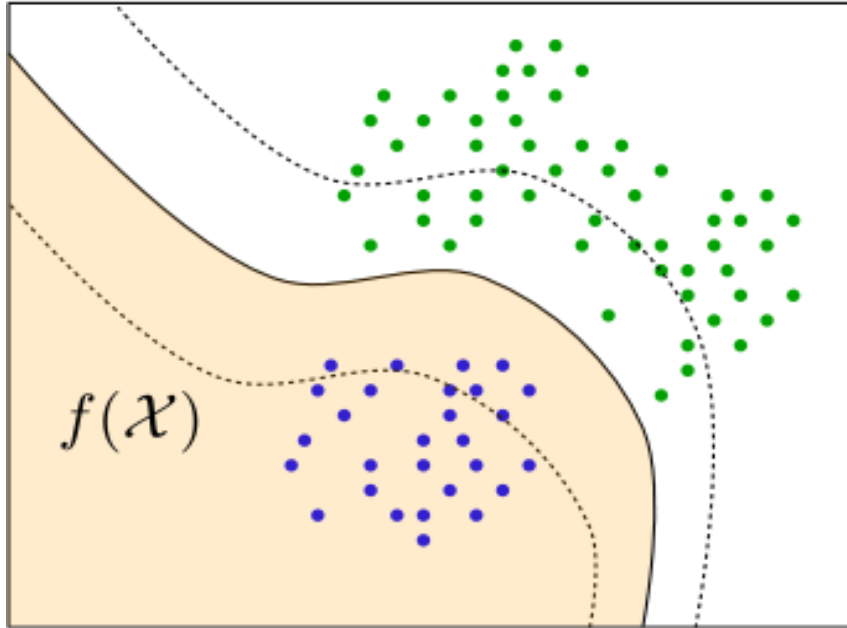
mechanistic
understanding



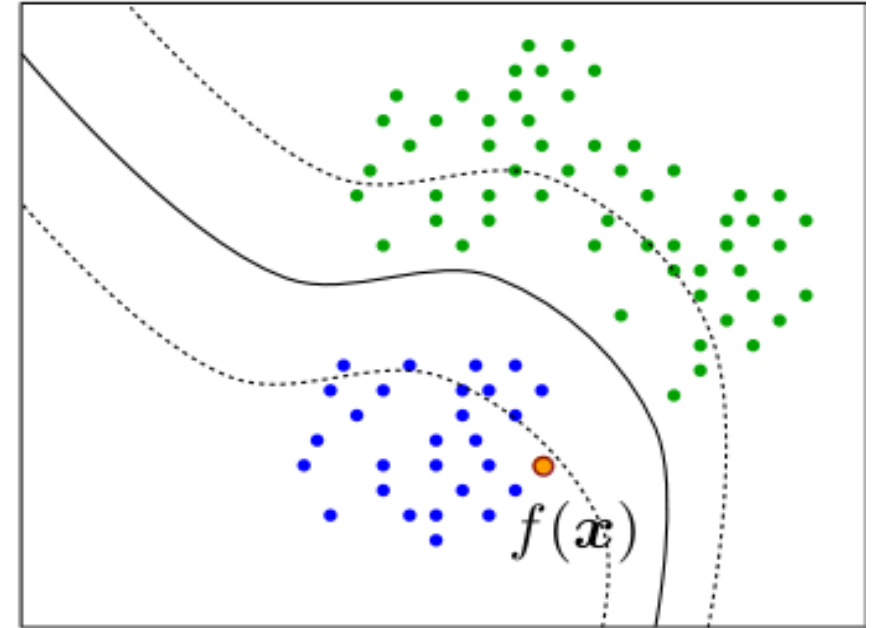
functional
understanding



model analysis

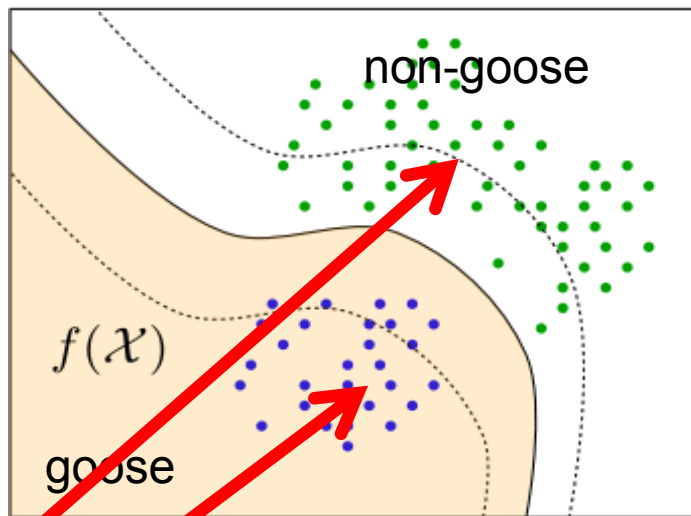


decision analysis



Approach 1: Class Prototypes

“How does a goose typically look like according to the neural network?”



Class prototypes

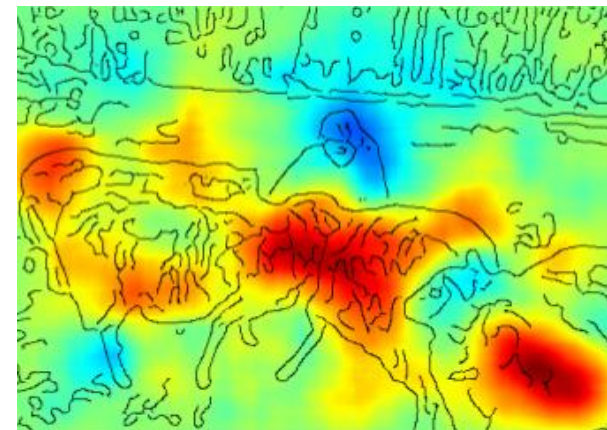
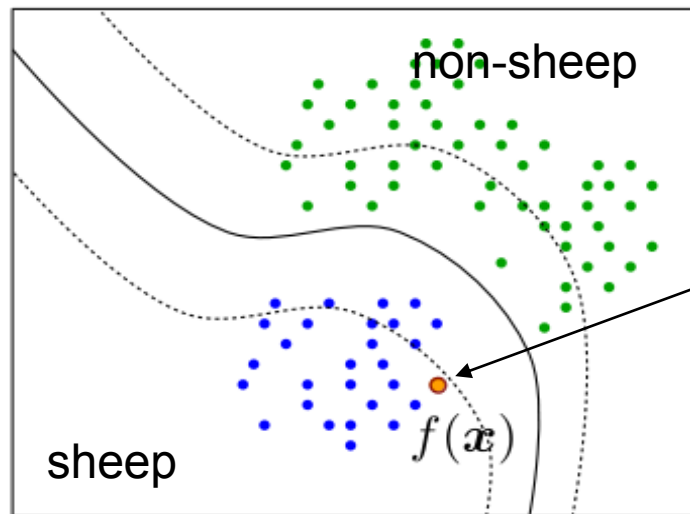
$$\arg \max_x f(x) + \text{reg.}$$



Image from **Symonian'13**

Approach 2: Individual Explanations

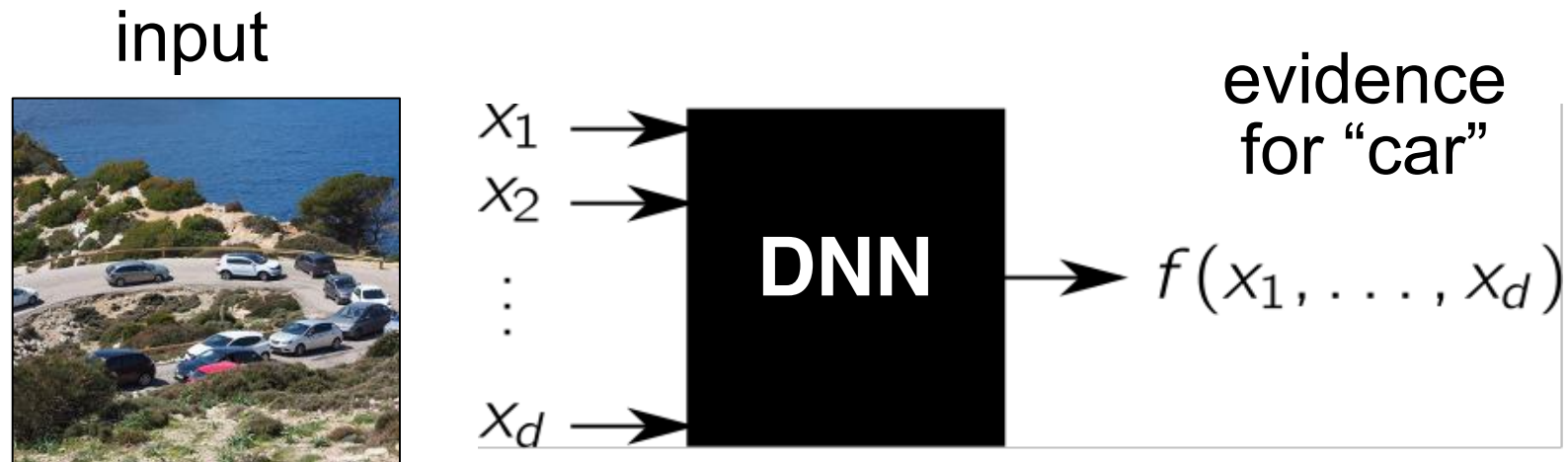
“Why is a given image classified as a sheep?”



heatmap = $LRP(x, f)$

Images from **Lapuschkin'16**

3. Sensitivity analysis



Sensitivity analysis: The relevance of input feature i is given by the squared partial derivative:

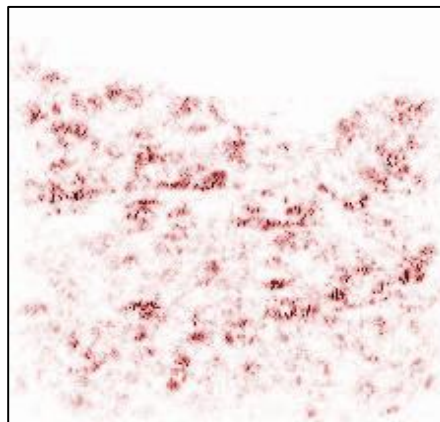
$$R_i = \left(\frac{\partial f}{\partial x_i} \right)^2$$

Understanding Sensitivity Analysis

Sensitivity analysis:



$$R_i = \left(\frac{\partial f}{\partial x_i} \right)^2$$



Problem: sensitivity analysis does not highlight cars

Observation:

$$\sum_{i=1}^d \left(\frac{\partial f}{\partial x_i} \right)^2 = \|\nabla_x f\|^2$$

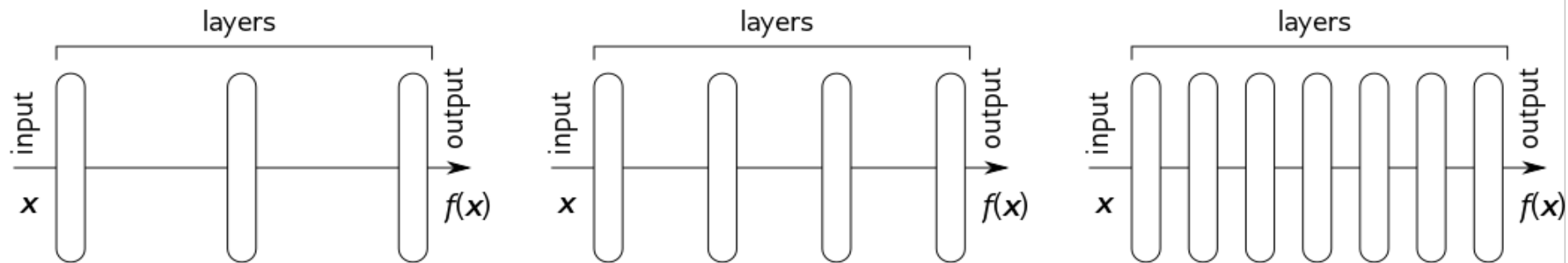
Sensitivity analysis explains a *variation* of the function, not the function value itself.

Sensitivity Analysis Problem: Shattered Gradients

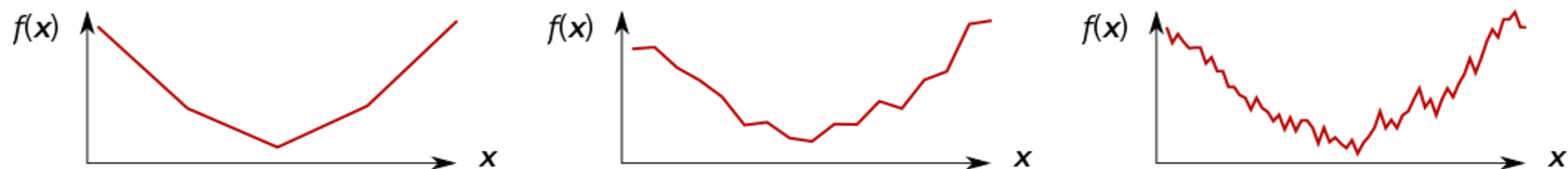
[Montufar'14, Balduzzi'17]

Input gradient (on which sensitivity analysis is based), becomes increasingly highly varying and unreliable with neural network depth.

Structure's view



Function's view (cartoon)



shallow



deep

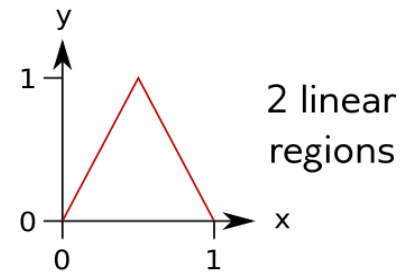
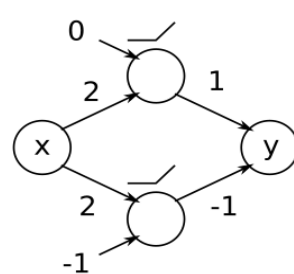
Shattered Gradients II

[Montufar'14, Balduzzi'17]

Input gradient (on which sensitivity analysis is based), becomes increasingly highly varying and unreliable with neural network depth.

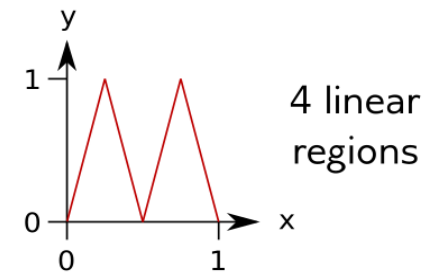
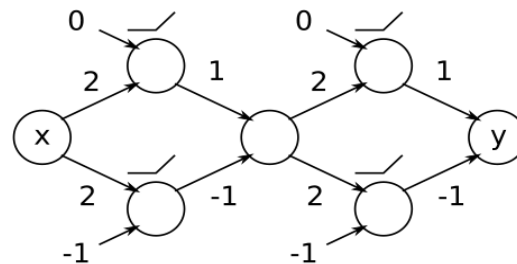
Example in $[0,1]$:

depth 1

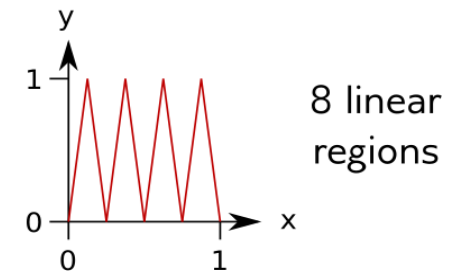
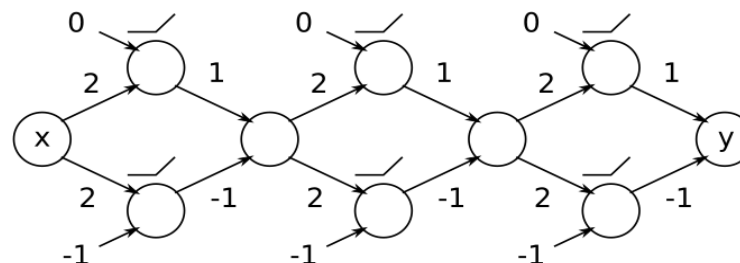


number of linear regions grows exponentially with depth

depth 2



depth 3



LPR is not sensitive to gradient shattering

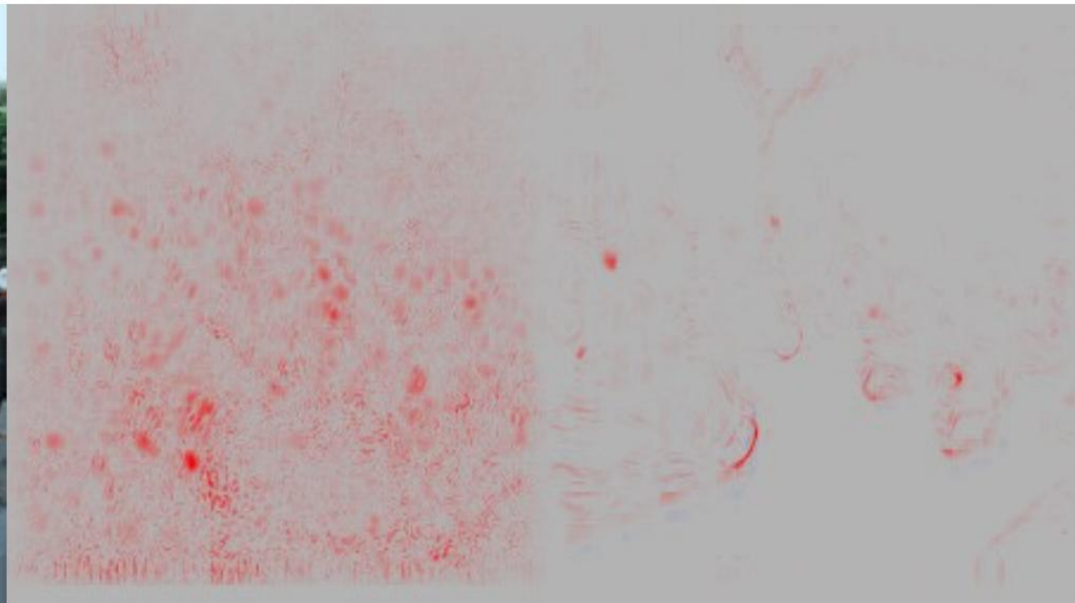
$$r_i = \underbrace{x_i \cdot \sum_j \frac{w_{ij}^+ r_j}{\sum_i x_i w_{ij}^+}}_{c_j}$$

LRP $\neq$ Gradient $\times$ Input

Image

Sensitivity ℓ_2

LRP



Explaining Neural Network Predictions

- Layer-wise relevance Propagation (LRP, **Bach et al 15**) first method to **explain** nonlinear classifiers
- based on generic **theory** (related to Taylor decomposition – deep taylor decomposition **M et al 16**)
 - applicable to any NN with monotonous activation, BoW models, Fisher Vectors, SVMs etc.

Explanation: “Which pixels contribute how much to the classification” (**Bach et al 2015**)
(what makes this image to be classified as a car)

$$f(x) = \sum_p h_p$$

Sensitivity / Saliency: “Which pixels lead to increase/decrease of prediction score when changed”
(what makes this image to be classified more/less as a car) (Baehrens et al 10, **Simonyan et al 14**)

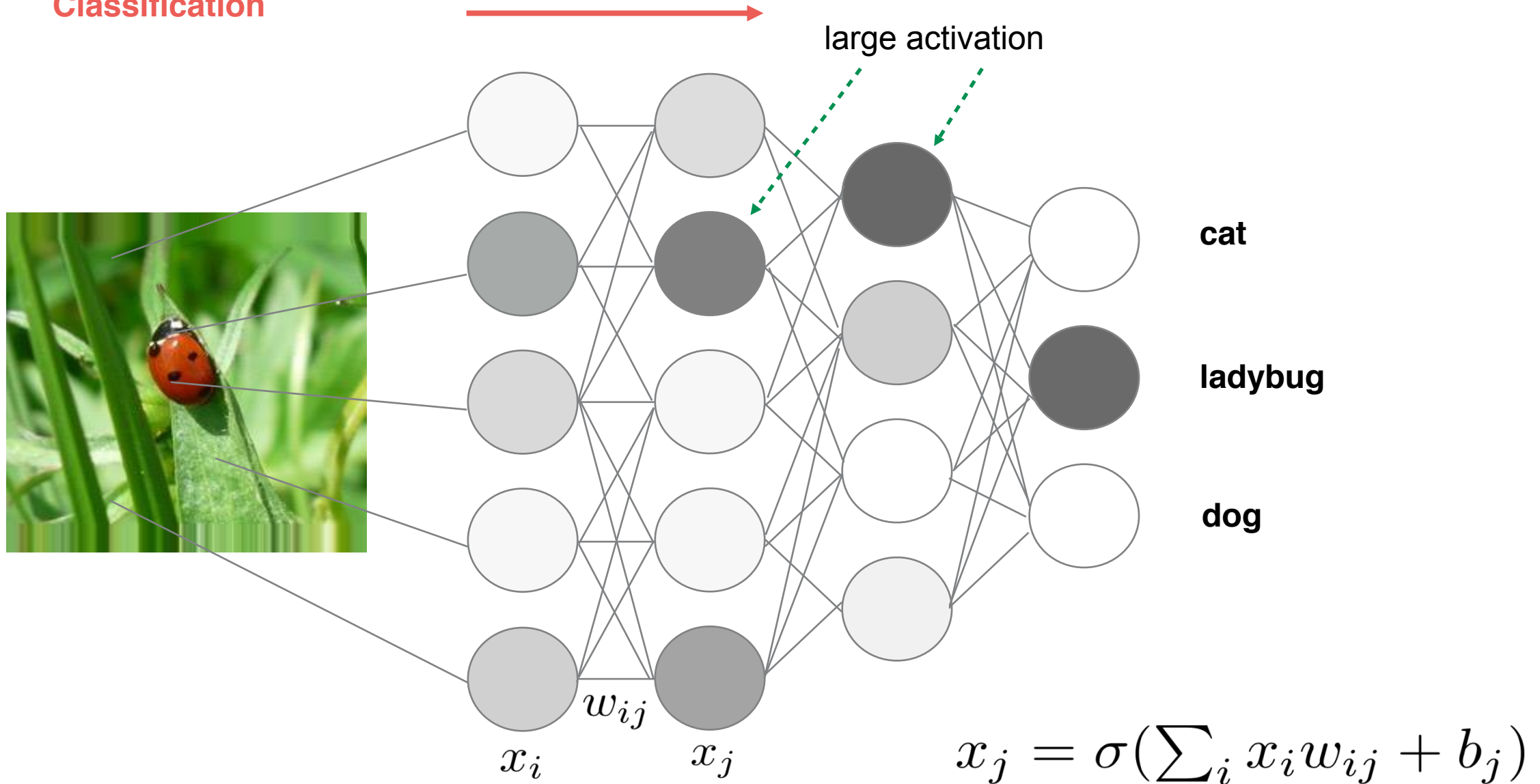
$$h_p = \left\| \frac{\partial}{\partial x_p} f(x) \right\|_{\infty}$$

Cf. Deconvolution: “Matching input pattern for the classified object in the image” (**Zeiler & Fergus 2014**,
(relation to $f(x)$ not specified)

Each method solves a **different** problem!!!

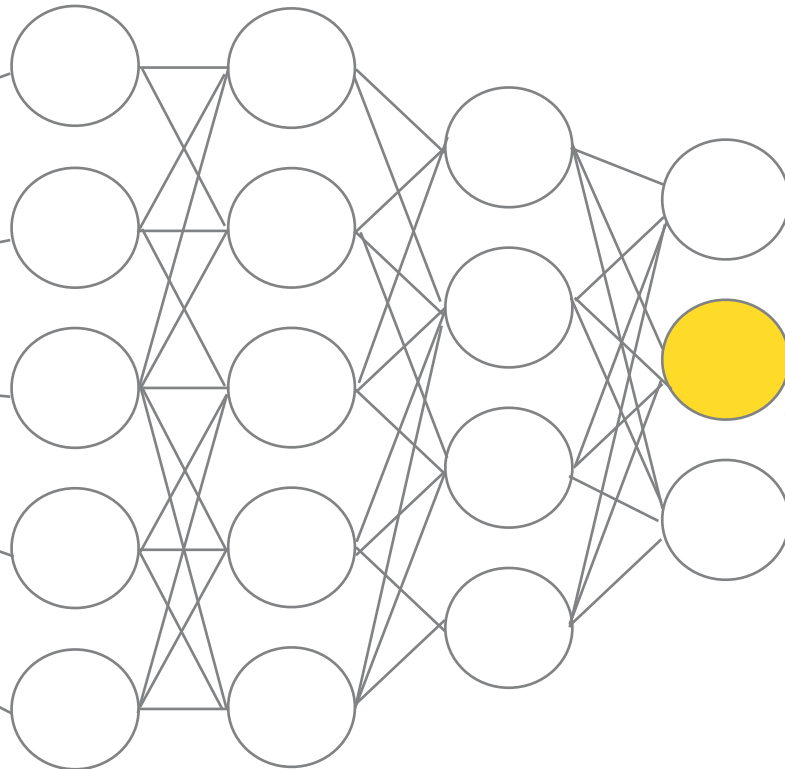
Explaining Neural Network Predictions

Classification



Explaining Neural Network Predictions

Explanation

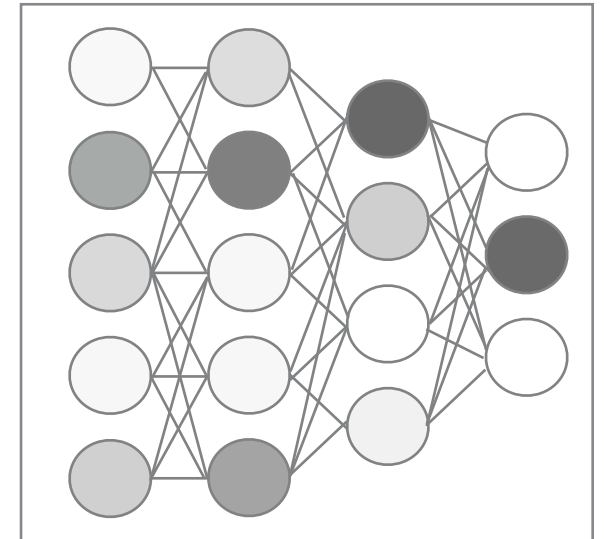


cat

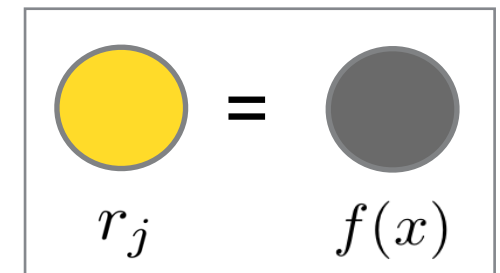
ladybug

dog

r_j

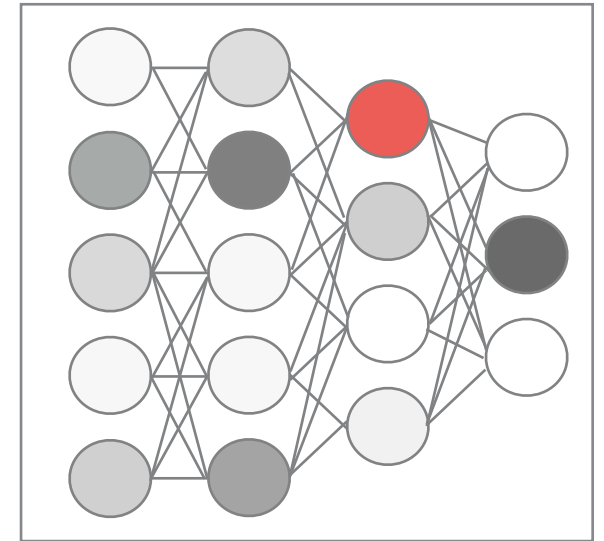
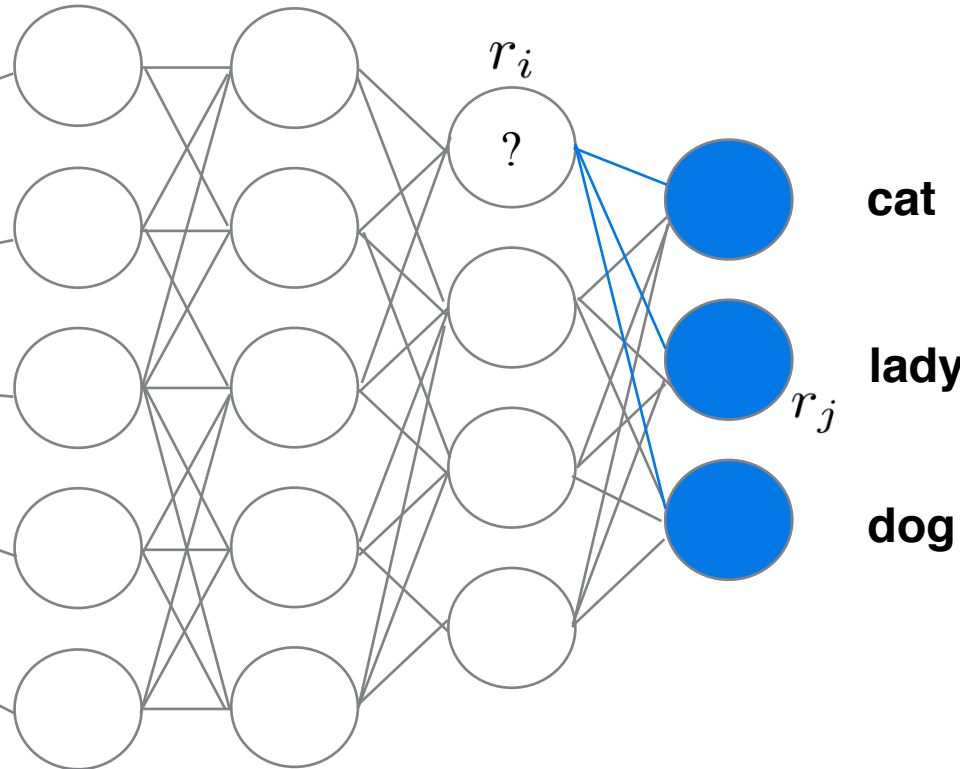


Initialization



Explaining Neural Network Predictions

Explanation



cat

ladybug

dog

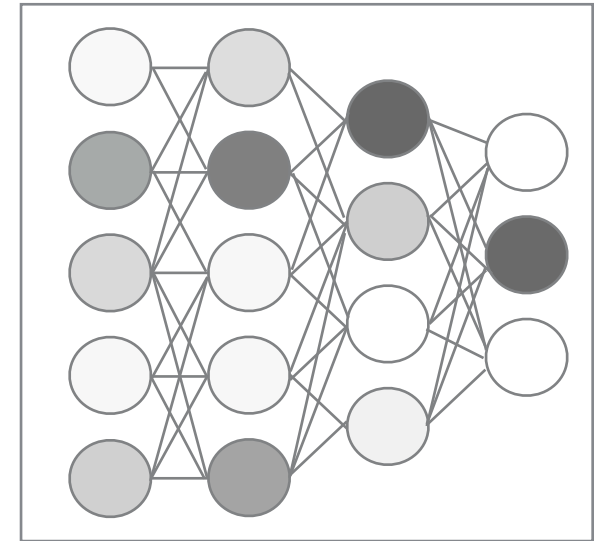
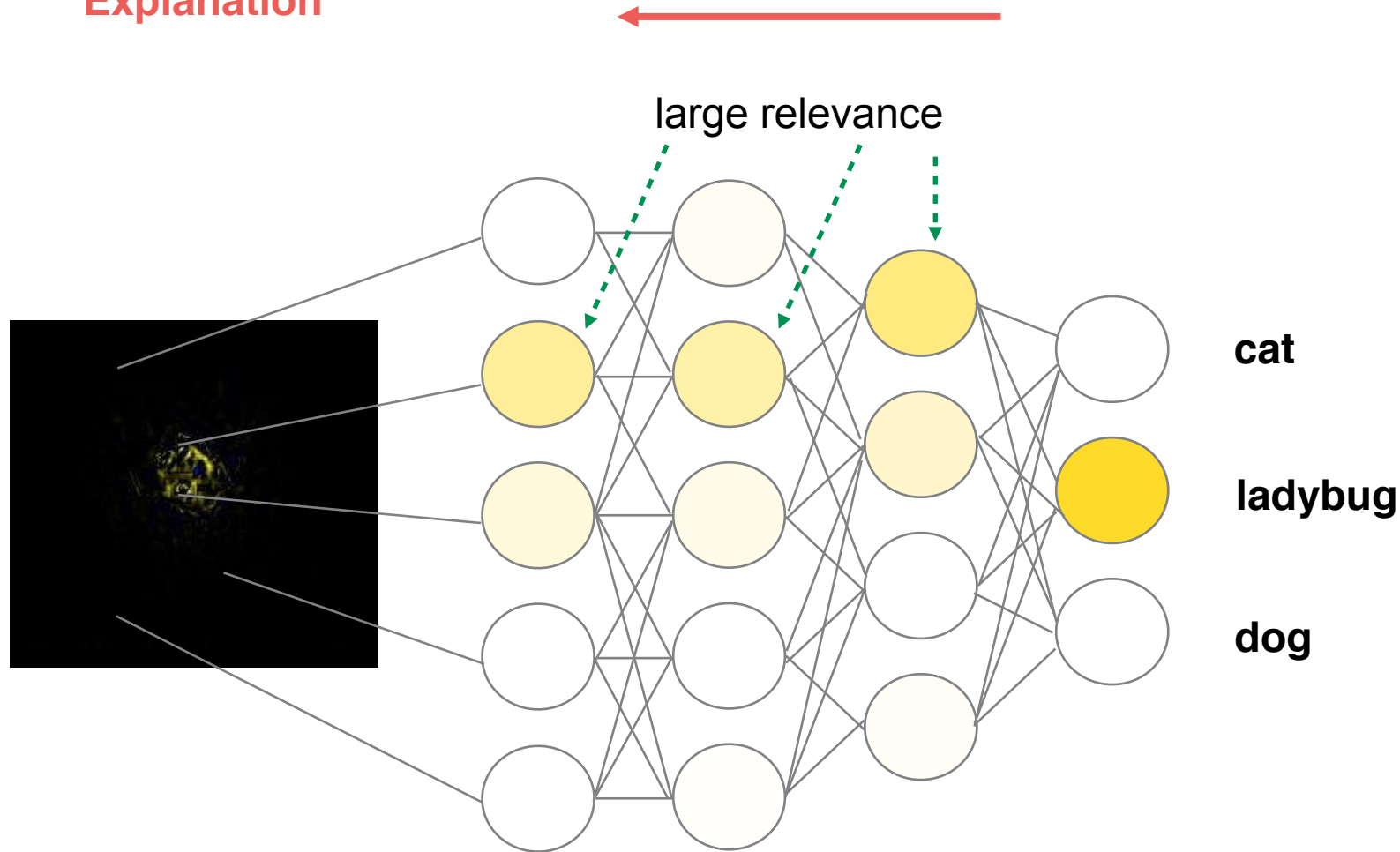
Theoretical interpretation
Deep Taylor Decomposition

r_i deper

$$r_i = x_i \cdot \underbrace{\sum_j \frac{w_{ij}^+ r_j}{\sum_i x_i w_{ij}^+}}_{C_j}$$

Explaining Neural Network Predictions

Explanation



Relevance Conservation Property

$$\sum_p r_p = \dots = \sum_i r_i = \sum_j r_j = \dots = f(x)$$

Historical remarks on Explaining Predictors

Gradients

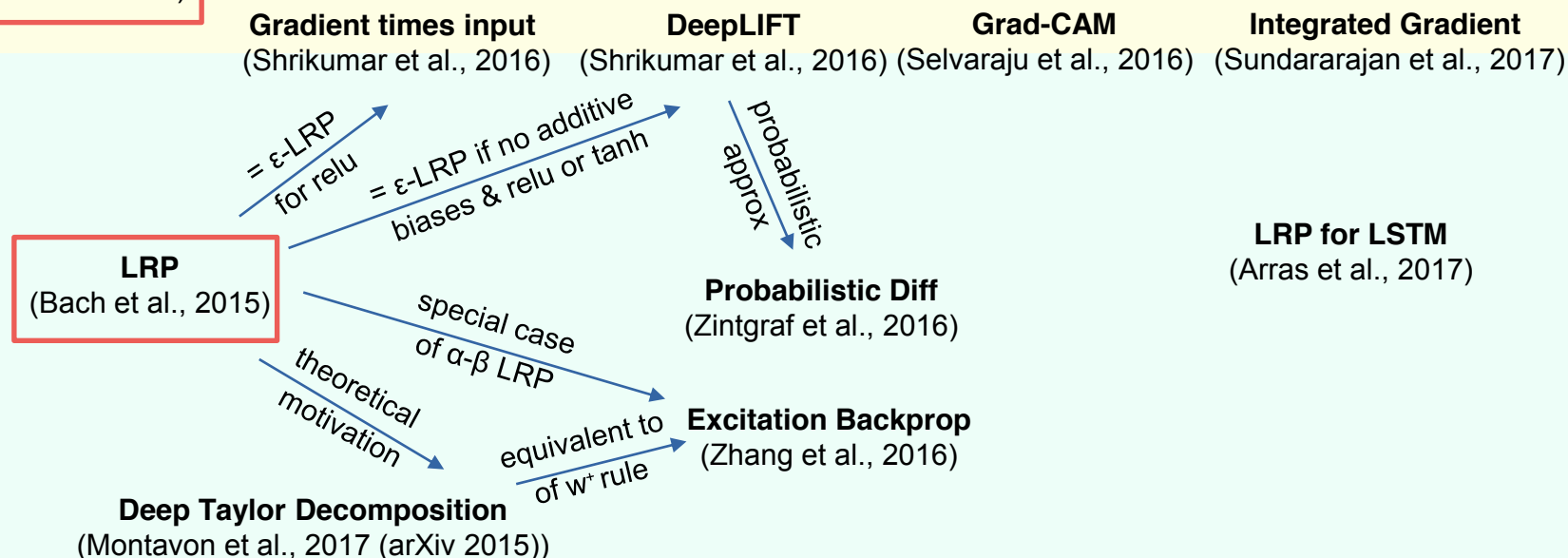
Sensitivity
(Baehrens et al. 2010)

Sensitivity
(Morch et al., 1995)

Sensitivity
(Simonyan et al. 2014)

Gradient vs. Decomposition
(Montavon et al., 2018)

Decomposition



Optimization

LIME
(Ribeiro et al., 2016)

Meaningful Perturbations
(Fong & Vedaldi 2017)

PatternLRP
(Kindermans et al., 2017)

Deconvolution

Deconvolution
(Zeiler & Fergus 2014)

Guided Backprop
(Springenberg et al. 2015)

Understanding the Model

Feature visualization
(Erhan et al. 2009)

Deep Visualization
(Yosinski et al., 2015)

Inverting CNNs
(Mahendran & Vedaldi, 2015)

Inverting CNNs
(Dosovitskiy & Brox, 2015)

RNN cell state analysis
(Karpathy et al., 2015)

Synthesis of preferred inputs
(Nguyen et al. 2016)

TCAV
(Kim et al. 2018)

Network Dissection
(Zhou et al. 2017)